## September 2008

# FSFA2100 — Fairchild Power Switch (FPS<sup>™</sup>) for Half-Bridge PWM Converters

## Features

- Optimized for Complementary Driven Half-Bridge Soft-Switching Converters
- Can be Applied to Various Topologies: Asymmetric PWM Half-Bridge Converters, Asymmetric PWM Flyback Converters, Asymmetric PWM Forward Converters, Active Clamp Flyback Converters
- High Efficiency through Zero-Voltage-Switching (ZVS)
- Internal SuperFET™s with Fast-Recovery Type Body Diode (t<sub>rr</sub>=120ns)
- Fixed Dead Time (200ns) Optimized for MOSFETs
- Up to 300kHz Operating Frequency
- Internal Soft-Start
- Pulse-by-Pulse Current Limit
- Burst-Mode Operation for Low Standby Power Consumption
- Protection Functions: Over-Voltage Protection (OVP), Over-Load Protection (OLP), Abnormal Over-Current Protection (AOCP), Internal Thermal Shutdown (TSD)

## Applications

- PDP and LCD TVs
- Desktop PCs and Servers
- Adapters
- Telecom Power Supplies

**Ordering Information** 

# Description

The growing demand for higher power density and low profile in power converter designs has forced designers to increase switching frequencies. Operation at higher frequencies considerably reduces the size of passive components, such as transformers and filters. However, switching losses have been an obstacle to highfrequency operation. To reduce switching losses and allow high-frequency operation, Pulse Width Modulation (PWM) with soft-switching techniques have been developed. These techniques allow switching devices to be softly commutated, which dramatically reduces the switching losses and noise.

FSFA2100 is an integrated PWM controller and SuperFET<sup>™</sup> specifically designed for Zero-Voltage-Switching (ZVS) half-bridge converters with minimal external components. The internal controller includes an oscillator, under-voltage-lockout, leading-edge blanking (LEB), optimized high-side and low-side gate driver, internal soft-start, temperature-compensated precise current sources for loop compensation and selfprotection circuitry. Compared with discrete MOSFET and PWM controller solution, FSFA2100 can reduce total cost; component count, size, and weight; while simultaneously increasing efficiency, productivity, and system reliability.

Part Number	Operating Junction Temperature	R <sub>ds(on_max)</sub>	Maximum Output Power without Heatsink (V <sub>IN</sub> =350~400V) <sup>(1,2)</sup>	Maximum Output Power with Heatsink (V <sub>IN</sub> =350~400V) <sup>(1,2)</sup>	Package	Eco Status
FSFA2100	-40 to +130°C	0.38Ω	200W	450W	9-SIP	RoHS

## Notes:

1. The junction temperature can limit the maximum output power.

2. Maximum practical continuous power in an open-frame design at 50°C ambient.

Ø For Fairchild's definition of "green" Eco Status, please visit: <u>http://www.fairchildsemi.com/company/green/rohs\_green.html</u>.





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# **Pin Definitions**

Pin #	Name	Description
1	V <sub>DL</sub>	This is the drain of the high-side MOSFET, typically connected to the input DC link voltage.
2	V <sub>FB</sub>	This pin is connected to the inverting input of the PWM comparator internally and to the opto-coupler externally. The duty cycle is determined by the voltage on this pin.
3	R <sub>T</sub>	This pin programs the switching frequency using a resistor.
4	CS	This pin senses the current flowing through the low-side MOSFET. Typically, negative voltage is applied on this pin.
5	SG	This pin is the control ground.
6	PG This pin is the power ground. This pin is connected to the source of the low-side MOS	
7	7 LV <sub>CC</sub> This pin is the supply voltage of the control IC.	
8	8 NC No connection.	
9	HVcc	This is the supply voltage of the high-side gate-drive circuit IC.
10	V <sub>CTR</sub>	This is the drain of the low-side MOSFET. Typically, a transformer is connected to this pin.

# **Absolute Maximum Ratings**

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.  $T_A=25^{\circ}C$  unless otherwise specified.

Symbol	Parameter		Min.	Max.	Unit	
V <sub>DS</sub>	Maximum Drain-to-Source Voltage (V <sub>DL</sub>	-V <sub>CTR</sub> and V <sub>CTR-PG</sub> )	600		V	
LV <sub>CC</sub>	Low-Side Supply Voltage		-0.3	25.0	V	
HV <sub>CC</sub> to V <sub>CTR</sub>	High-Side V <sub>CC</sub> Pin to Low-Side Drain Vo	oltage	-0.3	25.0	V	
HV <sub>CC</sub>	High-Side Floating Supply Voltage		-0.3	625.0	V	
V <sub>FB</sub>	Feedback Pin Input Voltage		-0.3	LV <sub>CC</sub>	V	
V <sub>CS</sub>	Current Sense (CS) Pin Input Voltage		-5.0	1.0	V	
V <sub>RT</sub>	R <sub>T</sub> Pin Input Voltage		-0.3	5.0	V	
dV <sub>CTR</sub> /dt	Allowable Low-Side MOSFET Drain Vol		50	V/ns		
PD	Total Power Dissipation <sup>(3)</sup>			12.0	W	
т	Maximum Junction Temperature <sup>(4)</sup>		+150	°C		
IJ	T <sub>J</sub> Recommended Operating Junction Temperature <sup>(4)</sup>		-40	+130		
T <sub>STG</sub>	Storage Temperature Range		-55	+150	°C	
MOSFET Sec	tion					
V <sub>DGR</sub>	Drain Gate Voltage ( $R_{GS}$ =1M $\Omega$ )		600		V	
V <sub>GS</sub>	Gate Source (GND) Voltage			±30	V	
I <sub>DM</sub>	Drain Current Pulsed			33	A	
	Continuous Drain Current	T <sub>C</sub> =25°C		11	•	
I <sub>D</sub>	Continuous Drain Current T <sub>c</sub> =100°C			7	A	
Package Sec	tion		4			
Torque	Recommended Screw Torque		5.	~7	kgf∙cm	

Notes:

3. Per MOSFET when both MOSFETs are conducting.

4. The maximum value of the recommended operating junction temperature is limited by thermal shutdown.

## **Thermal Impedance**

 $T_A=25^{\circ}C$  unless otherwise specified.

Symbol	Parameter		Unit
θ」	Junction-to-Case Center Thermal Impedance (Both MOSFETs Conducting)	10.44	°C/W

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
MOSFET Se	ection	l	1	1		
		I <sub>D</sub> =200μΑ, Τ <sub>Α</sub> =25°C	600			
BV <sub>DSS</sub>	Drain-to-Source Breakdown Voltage	I <sub>D</sub> =200μΑ, Τ <sub>Α</sub> =125°C		650		V
R <sub>DS(ON)</sub>	On-State Resistance	V <sub>GS</sub> =10V, I <sub>D</sub> =5.5A		0.32	0.38	Ω
t <sub>rr</sub>	Body Diode Reverse Recovery Time <sup>(5)</sup>	V <sub>GS</sub> =0V, I <sub>Diode</sub> =11.0A, dI <sub>Diode</sub> /dt=100A/µs		120		ns
Supply Sec	tion		1			
I <sub>LK</sub>	Offset Supply Leakage Current	HV <sub>CC</sub> =V <sub>CTR</sub> =600V			50	μA
$I_QHV_{CC}$	Quiescent HV <sub>CC</sub> Supply Current	(HV <sub>CC</sub> UV+) - 0.1V		50	120	μA
$I_QLV_{CC}$	Quiescent LV <sub>CC</sub> Supply Current	(LV <sub>CC</sub> UV+) - 0.1V		100	200	μA
I <sub>o</sub> HV <sub>cc</sub>	Operating HV <sub>cc</sub> Supply Current	$f_{OSC}$ =100KHz, V <sub>FB</sub> > 3V HV <sub>CC</sub> =17V		6	9	mA
(RMS Val	(RMS Value)	No switching, $V_{FB} < 1V$ HV <sub>CC</sub> =17V		100	200	μA
	Operating LV <sub>CC</sub> Supply Current	f <sub>OSC</sub> =100KHz, V <sub>FB</sub> > 3V		7	11	mA
(RMS Value)		No switching, $V_{FB} < 1V$		2	4	mA
UVLO Secti	on					
$LV_{CC}UV+$	LV <sub>CC</sub> Supply Under-Voltage Positive Go	ing Threshold (LV <sub>CC</sub> Start)	13.0	14.5	16.0	V
LV <sub>cc</sub> UV-	LV <sub>CC</sub> Supply Under-Voltage Negative G	oing Threshold (LV <sub>CC</sub> Stop)	10.2	11.3	12.4	V
$LV_{CC}UVH$	LV <sub>CC</sub> Supply Under-Voltage Hysteresis			3.2		V
HV <sub>CC</sub> UV+	HV <sub>CC</sub> Supply Under-Voltage Positive Go	bing Threshold (HV <sub>CC</sub> Start)	8.2	9.2	10.2	V
HV <sub>CC</sub> UV-	HV <sub>cc</sub> Supply Under-Voltage Negative G	oing Threshold (HV <sub>CC</sub> Stop)	7.8	8.7	9.6	V
HV <sub>cc</sub> UVH	HV <sub>CC</sub> Supply Under-Voltage Hysteresis			0.5		V
Oscillator a	nd Feedback Section					
V <sub>RT</sub>	V-I Converter Threshold Voltage		1.5	2.0	2.5	V
fosc	Output Oscillation Frequency	R <sub>T</sub> =27KΩ	94	100	106	KHz
D <sub>MAX</sub>	Maximum Duty Cycle	V <sub>FB</sub> =4V	45	50	55	%
D <sub>MIN</sub>	Minimum Duty Cycle	V <sub>FB</sub> =0V			0	%
$V_{FB}^{MAX}$	Maximum Feedback Voltage for $D_{MAX}$	D <sub>MAX</sub> ≥ 48%	2.7	3.0	3.3	V
I <sub>FB</sub>	Feedback Source Current	V <sub>FB</sub> =0V	370	470	570	μA
$V_{BH}$	Burst Mode High-Threshold Voltage		1.34	1.50	1.66	V
V <sub>BL</sub>	Burst Mode Low-Threshold Voltage		1.16	1.30	1.44	V
$V_{BHY}$	Burst Mode Hysteresis Voltage		0.1	0.2	0.3	V
t <sub>ss</sub>	Internal Soft-Start Time	f <sub>OSC</sub> =100kHz	10	15	20	ms

Continued on the following page...

6

# Electrical Characteristics (Continued)

 $T_A {=} 25^\circ C$  and  $LV_{CC} {=} 17 V$  unless otherwise specified.

Symbol	Parameter	<b>Test Conditions</b>	Min.	Тур.	Max.	Unit
Protectio	n Section					
I <sub>OLP</sub>	OLP Delay Current	V <sub>FB</sub> =5V	3.8	5.0	6.2	μA
V <sub>OLP</sub>	OLP Protection Voltage	V <sub>FB</sub> > 6V	6.3	7.0	7.7	V
V <sub>OVP</sub>	LV <sub>cc</sub> Over-Voltage Protection	LV <sub>CC</sub> > 21V	21	23	25	V
VAOCP	AOCP Threshold Voltage	∆V/∆t=-1V/µs	-1.0	-0.9	-0.8	V
t <sub>BAO</sub>	AOCP Blanking Time <sup>(5)</sup>	V <sub>CS</sub> < V <sub>AOCP</sub> ; ∆V/∆t=-1V/µs		50		ns
t <sub>DA</sub>	Delay Time (Low-Side) from $V_{AOCP}$ to Switch Off <sup>(5)</sup>	∆V/∆t=-1V/µs		250	400	ns
V <sub>LIM</sub>	Pulse-by-Pulse Current Limit Threshold Voltage	∆V/∆t=-0.1V/µs	-0.64	-0.58	-0.52	V
t <sub>BL</sub>	Pulse-by-Pulse Current Limit Blanking Time	$V_{CS} < V_{LIM};$ $\Delta V / \Delta t = -0.1 V / \mu s$		150		ns
t <sub>DL</sub>	Delay Time (Low-Side) from $V_{LIM}$ to Switch Off <sup>(5)</sup>	∆V/∆t=-0.1V/µs		450		ns
T <sub>SD</sub>	Thermal Shutdown Temperature <sup>(5)</sup>		110	130	150	°C
I <sub>SU</sub>	Protection Latch Sustain LV <sub>CC</sub> Supply Current	LV <sub>CC</sub> =7.5V		100	150	μA
V <sub>PRSET</sub>	Protection Latch Reset LV <sub>CC</sub> Supply Voltage		5			V
Dead-Tim	e Control Section					
DT	Dead Time <sup>(6)</sup>			200		ns

Notes:

5.

This parameter, although guaranteed, is not tested in production. These parameters, although guaranteed, are tested only in EDS (wafer test) process. 6.



**Typical Performance Characteristics** 

8



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## **Functional Description**

**1. Internal Oscillator**: FSFA2100 employs a currentcontrolled oscillator as shown in Figure 17. Internally, the voltage of the  $R_T$  pin is regulated at 2V and the charging/discharging current for the oscillator capacitor  $C_T$  is determined by the current flowing out of the  $R_T$  pin ( $I_{CTC}$ ). When the  $R_T$  pin is pulled down to the ground with a resistor  $R_{SET}$ , the switching frequency is fixed as:



Figure 17. Current Controlled Oscillator

**2. PWM Control**: Figure 18 shows the typical control circuit configuration. The opto-coupler transistor should be connected to the  $V_{FB}$  pin in parallel with the feedback capacitor to control the duty cycle.



Figure 18. PWM Control Configuration

Figure 19 shows the internal block diagram for PWM operation. Duty cycle is controlled by comparing the feedback voltage to the triangular signal with a range from 1V to 3V.



Figure 19. Internal PWM Block Diagram

**3. Protection Circuits**: The FSFA2100 has Overload Protection (OLP), Abnormal Over-Current Protection (AOCP), Over-Voltage Protection (OVP), and Thermal Shutdown (TSD) self-protective functions. The OLP and OVP are auto-restart mode protections, while the AOCP and TSD are latch-mode protections, as shown in Figure 20.

Auto-restart mode protection: Once the fault condition is detected, the switching is terminated and the MOSFETs remain off. When  $LV_{CC}$  falls down to  $LV_{CC}$  stop voltage of around 11V, the protection is reset. The FPS resumes normal operation when  $LV_{CC}$  reaches the start voltage of about 14V.

*Latch-mode protection:* Once this protection is triggered, the switching is terminated and the MOSFETs remain off. The latch is reset only when  $LV_{CC}$  is discharged below 5V.



### Figure 20. Protection blocks

Low-side MOSFET current should be sensed for Pulseby-pulse current limit and AOCP. The FSFA2100 senses drain current as a negative voltage, as shown in Figure 21 and Figure 22. Half-wave sensing allows low-power dissipation in the sensing resistor, while full-wave sensing has less noise in the sensing signal.





Figure 22. Full-Wave Sensing

3.1 Pulse-by-Pulse Current Limit: In normal operation, the duty cycle of the low-side MOSFET is determined by comparing the internal triangular signal with the feedback voltage. However, the low-side MOSFET is forced to turn off when the current sense pin voltage reaches -0.58V. This operation limits the drain current below a pre-determined level to avoid the destruction of the MOSFETs.

3.2 Abnormal Over-Current Protection (AOCP): If one of the secondary rectifier diodes is short-circuited, large current with extremely high di/dt can flow through the MOSFET before OCP or OLP is triggered. AOCP is triggered with a very short shutdown delay time when the sensed voltage drops below -0.9V. This protection is latch mode and reset only when  $LV_{CC}$  is pulled below 5V.

3.3 Overload Protection (OLP): Overload is defined as the load current exceeding its nominal level due to an unexpected abnormal event. In this situation, a protection circuit should trigger to protect the power supply. However, even when the power supply is in the normal condition, the OLP circuit can be triggered during the load transition. To avoid this undesired operation, the OLP circuit is designed to trigger only after a specified time to determine whether it is a transient situation or a true overload situation. Because of the pulse-by-pulse current limit capability, the maximum peak current through the MOSFET is limited; and, therefore, the maximum input power is restricted with a given input voltage. If the output consumes more than this maximum power, the output voltage (V<sub>0</sub>) decreases below the nominal voltage. This reduces the current through the opto-coupler diode, which also reduces the opto-coupler transistor current, increasing the feedback voltage (V<sub>FB</sub>). If V<sub>FB</sub> exceeds 3V, D1, which is illustrated in Figure 19, is blocked and the OLP current source starts to charge C<sub>B</sub> slowly, as shown in Figure 23. In this condition, V<sub>FB</sub> continues increasing until it reaches 7V, then the switching operation is terminated, as shown in Figure 23. The delay time for shutdown is the time required to charge  $C_B$  from 3V to 7V with 5µA, as given by:

$$t_{delay} = \frac{(7V - 3V) \times C_B}{5\mu A}$$
(2)

A 30 ~ 50ms delay time is typical for most applications.



3.4 Over-Voltage Protection (OVP): When the LV<sub>CC</sub> reaches 23V, OVP is triggered. This protection is enabled when using an auxiliary winding of the transformer to supply LV<sub>CC</sub> to FPS.

3.5 Thermal Shutdown (TSD): The MOSFETs and the control IC are built in one package. This allows the control IC to detect the abnormal over-temperature of the MOSFET. If the temperature exceeds approximately 130°C, the thermal shutdown triggers.

4. Soft-Start: At startup, the duty cycle starts increasing slowly to establish the correct working conditions for transformers, inductors, and capacitors. The voltage on the output capacitors is progressively increased to smoothly establish the required output voltage. Soft-start time is internally implemented for 15ms (when the operating frequency is set to 100kHz.) In addition, to help the soft-start operation, a capacitor and a resistor would be connected on the  $R_T$  pin externally, as shown in Figure 24. Before the power supply is powered on, the capacitor C<sub>SS</sub> remains fully discharged. After power-on, C<sub>SS</sub> becomes charged progressively by the current

**FSFA2100** 

through the  $R_T$  pin, which determines the operating frequency. The current through the  $R_T$  pin is inversely proportional to the total impedance of the connected resistors. The total impedance at startup is lower than that of the normal operation because  $R_{SS}$  is added on  $R_{SET}$  in parallel, which means the operating frequency decreases continuously from higher to nominal. Eventually  $C_{SS}$  is fully charged to the  $R_T$  pin voltage and the operating frequency is determined by  $R_{SET}$  only.

During the charging time of  $C_{SS}$ , the operating frequency is higher than during normal operation. In asymmetric half-bridge converters, a switching period contains powering and commutation periods. The energy cannot be transferred to the output side during commutation period. Since the DC link voltage applied to the V<sub>DL</sub> pin and the leakage inductance of the main transformer are fixed, the powering period over the switching period is shorter in high switching frequencies. As C<sub>SS</sub> is charged, the switching frequency decreases and the powering period over the switching period increases as well. It is helpful to start SMPS softly with the internal soft-start time together.



**5. Startup:** Due to the imbalance of the turn-off resistance between the high- and low-side MOSFETs, the voltage across the DC blocking capacitor cannot be predicted at startup. Additionally, the high-side MOSFET starts with a large duty cycle since the duty cycle of the low-side MOSFET increases step-by-step during soft-start time. Therefore, in the case where high voltage is already charged in the DC blocking capacitor due to the higher turn-off resistance of the high-side MOSFET before startup, a large primary current could flow through the high-side MOSFET during turn-on time after startup. For the high-side MOSFET, a long duty cycle and high

applied voltage make an excessive primary current. When the high-side MOSFET turns off, the primary current flows back to the DC link capacitor through the body diode of the low-side MOSFET. It keeps the same status even after turning on and off the low-side MOSFET. When the high-side MOSFET turns on again, a huge current can flow from the DC link capacitor through the channel of the high-side MOSFET and body diode of the low-side one due to the reverse recovery. It may induce unexpected noise into CS pin.

To avoid this issue, the voltage across the DC blocking capacitor must be low enough. In general, two resistors with several MHz can be added on the drain-to-source terminals of each MOSFET to divide the DC link voltage.

**6. Burst Operation**: To minimize power dissipation in standby mode, the FSFA2100 enters burst-mode operation. As the load decreases, the feedback voltage decreases. As shown in Figure 25, the device automatically enters burst mode when the feedback voltage drops below  $V_{BL}$  (1.3V). At this point, switching stops and the output voltages start to drop at a rate dependent on standby current load. This causes the feedback voltage to rise. Once it passes  $V_{BH}$  (1.5V), switching resumes. The feedback voltage then falls and the process repeats. Burst-mode operation alternately enables and disables switching of the MOSFETs, thereby reducing switching loss in standby mode.



Application	FPS™ Device	Input Voltage Range	Rated Output Power	Output Voltage (Rated Current
LCD TV	FSFA2100	400V	200W	25V-8A
Reduced EM	stem Reliability with	input) p-Voltage-Switching (ZVS) Various Protection Functions	S	
+ V <sub>IN</sub> =400V (from PFC output) + Z	C107 + 0.68µF ZZZ R105 27k C104 C104 C104 68nF C R102 C104 R102 C104 R102 C104	RT FB Control IC VCTR Control VCTR Control Contro		C201 C202 2200µF 2200µF 35V 35V ++
		<sup>₀₂</sup> <sup>♥</sup> Figure 26. Typical Applica	ation Circuit	

# Typical Application Circuit (Continued)

- Core: EER3542 (Ae=107 mm<sup>2</sup>)
- Bobbin: EER3542 (Horizontal)





Figure 27. Core and Winding

	$\text{Pin}(\mathbf{S} \to \mathbf{F})$	Wire	Turns	Winding Method
Np	8 → 1	0.12φ×30 (Litz wire)	50	Solenoid winding
N <sub>s1</sub>	16  ightarrow 13	0.1φ×100 (Litz wire)	8	Solenoid winding
N <sub>s2</sub>	$12 \rightarrow 9$	0.1φ×100 (Litz wire)	8	Solenoid winding

	Pin Specification		Remark
Inductance	1-8	630μH ± 5%	100kHz, 1V
Leakage	18	45μH ± 10%	Short one of the secondary windings





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